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## **EDUCATION**

### University of Colorado, Boulder

Master of Science in Electrical Engineering (Specialization in Embedded Systems and IoT Firmware Design) 3.8/4 Courses: ECEN 5813 - Principles of Embedded Software, ECEN 5823 - IoT Embedded Firmware Desian, ECEN 5013 - Advanced Embedded Software Development, ECEN 5623 Real-Time Embedded Systems, ECEN 5122 Wireless Local Area Networks.

### SKILLS

- Languages: C, C++, Python, Bash, Embedded C. •
- Protocols/Standards: I2C, SPI, TCP/IP, UDP, MQTT, BLE, 802.11.
- Design/Dev Tools: Keil, Eagle, gdb, MCU Expresso, Simplicity Studio, CCS, AVR-Studio, Git, Wire Shark, FreeRTOS, Build root.
- OS Concepts: Virtualization, Multi-Threading, Task Synchronization, Linux Device Drivers, Scheduling Policies, Concurrency.

## **PROFESSIONAL EXPERIENCE**

### Larsen and Toubro Ltd, Mumbai, India

Sr. Systems Design and Integration Engineer

- Effectuated narrow band mesh technology for smart electrical meters with 74% cost reduction in lease lines. Indore, India
- Installed & Commissioned Building Automation & Control System worth \$7.6bn for Qatar Rail. Doha, Qatar
- Implemented PID control model across the gas line to control its process variables along with its SCADA. Tatweer, Bahrain Designed GSM based RTU system to transmit Pressure and Temperature data-points from in plant transmitters. OGC, Oman

# **Department of Remote Handling and Robotics, BARC-Mumbai**

Research and Project Trainee

- Designed Servo drive models and studied its response for implementing haptic feedback for telerobotic manipulators.
- Transmitted feedback data Implementing Interoperable Teleoperation Protocol wrapped in low overhead UDP packet.
- Department of Radiation Detection and Instrumentation, BARC-Mumbai

Research and Project Trainee

- Developed embedded firmware and data logging system for gamma-radiation detector implementing TI-MSP430 controller.
- Calibrated the electrical pulses in the Sievert scale implementing on-board JTAG interface.

## ACADEMIC PROJECTS

## Linux Based Remote Health Monitoring System

- Built custom Linux image to support server-client model over a Wi-Fi network using MQTT for exchange of messages.
- Implemented multi-threaded server with mutexes to handle multiple requests from client and host the data on a web page.
- Implemented logging functionality for sensor data in case of network failure and retransmit them to the server over MQTT.
- Designed a Built-in-Startup-Test (BIST) for flawless system bring-up and Unit Tested each module to ensure system stability.

## **Time Lapse Image Acquisition**

- Designed sequencer for real time threads adhering to rate monotonic scheduling policy to capture images 1 Hz and 10 Hz.
- Implemented I/O decoupling to buffer data for best effort services using circular buffer resulting in low jitter and drift.
- Time stamped and overlaid user data into the frames while compressing frames in jpg format with a size reduction of 250%.

## **Bluetooth Low Energy based Smart Warehouse System**

- Acquired AQI data from CCS801 CO2 sensor over I2C bus on LPN and catered GATT-characteristic services to a friend node.
- Implemented state machine model and load power management while acquiring data from the sensor at regular intervals.
- Effectuated deep sleep states and low energy timer, thus reducing the average current consumed by the system by 200%.
- Integrated iBecons with LPN by dissociating the beacon frames and posting the head count in its vicinity to the Friend Node.

## **Embedded Signal Generator and Analyzer implementing FreeRTOS**

- Generated waveforms with varying range and time using a lookup table, achieving a 70% reduction in computation time. •
- Implemented DMA transfer from ADC buffer to memory using task scheduling while printing DSP report on serial interface.
- Exploited xQueuing feature in FreeRTOS to create DSP buffer along with semaphores and mutexes for task synchronization. •
- Developed bare-metal drivers for SPI, ADC, DAC, I2C and DMA along with a tabular state machine model for FreeRTOS tasks.

## Self-Stabilizing Platform

- Jul 2016 Apr 2017 Sensor Fusion of accelerometer and gyroscope to yield real-time yaw, pitch, roll of the platform via I2C interface.
- Compensated random drifts in time-varying mean samples of the sensor implementing Kalman Filter.
- Implemented PID control for error correction of real-time yaw, pitch and roll values. .
- Implemented serial link for 3D simulation of the platform and graphical analysis of the model using processing software.

## AVR Based Oscilloscope

- Implemented AVR ATMEGA 32 controller along with a GLCD screen to display waveforms of input electrical signals.
- Designed amplifier and low pass filter for the input signal while feeding its output to the ADC pin of the micro-controller. Provided the provision of compressing or expanding of the signal along time axis along with the representation of real-time
- frequency and amplitude of input signal by the means of push-button switches.

## WORKSHOPS AND CERTIFICATIONS

- Raspberry Pi Platform and Python Programming using Raspberry Pi University of California, Irvine through Coursera. .
- Programming for Everybody (Getting Started with Python)- University of Michigan through Coursera.
- Python Data Structures University of Michigan through Coursera.

Jan 2020 – May 2020

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## Sept 2019 – Dec 2019

Sept 2019 – Dec 2019

Jan 2016 - Mar 2016

Jul 2017 - Jul 2019

Dec 2015 - Jan 2016

Jun 2014 - Jul 2014